



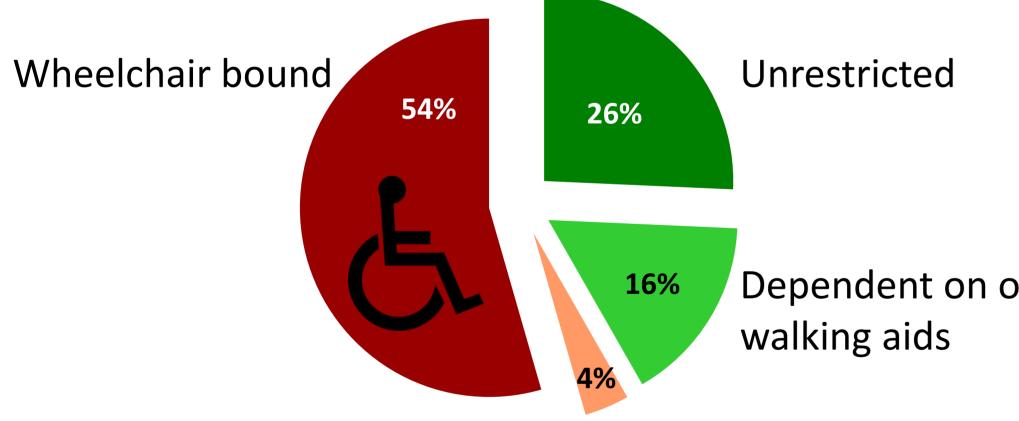
Aim

- Evaluate whether prolonged robot-assisted training leads to a better walking outcome with incomplete spinal cord injury (SCI), wh initially unable to walk independently (i.e. E according to the International Standards for Neurological Classification of SCI-ISNCSCI)
- Evaluate whether such training is feasible or associated with undesirable effects

Background

A large proportion of patients regain ambulatory fur year after onset of SCI (fig. 1)². However, during the months most patients are unable to walk without su

Fig1: Ambulatory function 1 year after SCI (n=393)²



Dependent on physical assist

- Training effects depend on the intensity (duration, f the training. E.g. augmented training results in a bet function in patients with stroke³.
- Robot-assisted locomotor training is applied early at which allows for long training duration.

Affiliations

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Dose-Response Relationship of Locomotor Training in Patients with Spinal Cord Injury¹: **Preliminary Results**

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e in patients ho are B and C for or is	 Conclusions Longer training sessions using a robotic device Are feasible Are not associated with undesirable effects Results show a trend towards a positive dose-responselationship However, there was a larger proportion of patients with a motor incomplete SCI (i.e. ISNCSCI: C) in the intensive training group 		 Implications The duration of a standard training session needs to be re-addressed Results indicate that more intensive training leads to a better outcome 					
	Methods Sample		Results					
function one	Patients with an acute incomplete SCI (within 60 days after				Intervention	Control	All	
ne first 3	injury)	Sample	Tetra	В	1	4	5	
support.		-		С	6	1	7	
	Intervention/ Control		Para	В	2	2	4	
	Random allocation to either:			С	0	1	1	
	 intensive training (session duration ≥ 50 minutes) or 						Test statistic	
	 standard training (session duration ≤ 25 minutes) 	Training	Number Duration [min] Week 0		34.9±6.0 (26-40)	33.8±6.8 (22-40)	n.s.	
					48.3±3.2 (1-78)	24.9±0.6 (1-37)	p=0.01	
	Outcomes	WISCI			0 (0-0)	0 (0-0)	n.s.	
n orthotics and/ or	Comparison after 8 weeks of training:		Week 8 Within group		10.5 (0-19)	4 (0-20)	n.s.	
	 Adherence to the intervention protocol 				p<0.05	n.s. (p=0.109)	D C	
	 Walking ability (Walking Index for SCI-WISCI), 		Week 8		2.5 (1-4)	3.5 (0-5)	n.s.	
	0=not able to walk, 20= able to walk independently	RPE Adverse	Average	с	6 (1-10) No adverse events due	6.5 (1-10)	n.s.	
, frequency) of better walking after injury	 Patients' global impression of change (PGIC), 0= much better, 5= no change, 10= much worse Rate of perceived exertion (RPE) 1=very light, 10= very, very hard Occurrence of adverse events 	Tetra: Tetraple PGIC: Patients	Tetra: Tetraplegia; Para: Paraplegia; WISCI: Walking Index for Spinal Cord Injury; PGIC: Patients Global Impression of Change; RPE: Rate of Perceived Exertion. Figures are counts or mean ± standard deviation or median and (range).					

References

¹ Wirz M, Bastiaenen C, deBie R, Dietz V. Effectiveness of Automated Locomotor Training in Patients with Acute Incomplete Spinal Cord Injury: A Randomized Controlled Multicenter Trial. BMC Neurol. 2011 May 27;11:60

² van Hedel HJ, Wirz M, Dietz V. Standardized assessment of walking capacity after spinal cord injury: The European network approach. Neurol Res. 2008; 30(1):61-73 ³ Kwakkel G, Kollen B, Twisk J: Impact of time on improvement of outcome after stroke. Stroke; a journal of cerebral circulation 2006, 37(9):2348-2353

FNAC European Multicenter Study about Spinal Cord Injury